# STATISTICALLY (OPTIMAL) ESTIMATORS OF SEMIVARIANCE: A CORRECTION OF JOSEPHY-ACZEL'S PROOF 

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#### Abstract

Semivariance is an intuitive risk measure because it concentrates on the shortfall below a target and not on total variation. To successfully use semivariance in practice, however, a statistical estimator of semivariance is needed; Josephy and Aczel provide such an estimator. Unfortunately, they have not correctly proven asymptotic unbiasedness and mean squared error consistency of their estimator since their proof contains a mistake. This paper corrects the computational mistake in Josephy-Aczel's original proof and, that way, allows researchers and practitioners in the field of downside portfolio selection, hedging, downside asset pricing, risk measurement in a regulatory context, and performance measurement to work with a meaningfully specified downside measure.


Keywords: risk analysis, semivariance, statistical estimation.

## 1. Introduction to the problem

On the one hand, semivariance - lower partial moment 2 - is an intuitive risk measure because it concentrates on the shortfall below a target and not on total variation. Therefore it is used in downside portfolio selection (pioneered by [Markowitz 1959; Jin, Markowitz, Zhou 2006]) for an overview of and further developments in downside portfolio selections, hedging [Demirer, Lien 2003; Cotter, Hanly 2006], downside asset pricing (pioneered by [Bawa, Lindenberg 1977; Ang, Chen, Xing 2006] for an overview of and further developments in downside betas), risk measurement in a regulatory context [Brooks, Persand 2003], and performance measurement (for stocks, e.g. [Hoechner, Reichling Schulze 2017], for the effects of environmental, social, and governance issues [Hoepner et al. 2018], and for hedging [Lee, Chien 2010]. On the other hand, the formalism behind lower partial moments is identical to the computation of Conditional Value at Risk [Demirer, Lien, Shaffer 2005, p. 56] were the first to emphasize this connection - and stochastic dominance [Davidson, Duclas 2000, p. 1444].

To successfully use semivariance and its formal companion in practice, a statistical estimator of semivariance is needed. In this connection, two aspects must be addressed: first, it must be determined when semivariance is triggered; second, the target must be estimated, for example, if mean is used as target. In the latter case, both aspects will be interrelated since the estimator of semivariance is triggered based on the sample average instead of the unknown true mean. In that case, only the trigger problem exists, Davidson and Duclas [2000] derive a rather general estimator where observations just have to be independent, but not identically distributed, but are less successful for the interrelated case: they determine an estimator for lower partial moment 1 for identically distributed and independent observations, but not an estimator for semivariance. Unfortunately, this interrelated case is the economically relevant one. For example, Lewis [1990] recommends the mean as target for lower partial moment based performance measurement. Barrett and Donald [2003, p. 71] stress that it is important to compare more than one point when ranking alternatives based on stochastic dominance - using the mean as target might mitigate this problem.

Only the vastly underappreciated paper by Josephy and Aczel [1993] provides a statistical estimator for semivariance where target equals mean and observations are independent and identically distributed. Even though independent and identically distributed observations are rather mundane and do not seem to be representative of modern-day econometrics [Josephy, Aczel 1993] is still the most advanced paper in the field of estimating semivariance with mean as target.

Unfortunately, Josephy and Aczel [1993] have not correctly proven the asymptotic unbiasedness and mean squared error consistency of their estimator. In their proof, they mistakenly assume terms to be 0 that are in fact unequal to 0 .

Given this setting, the goal of this paper is to identify and correct the mistake in Josephy-Aczel's [1993] derivation. In this connection, we deviate from their (1993) original proof of asymptotic unbiasedness and mean squared error consistency. Their computational mistake results in several missing terms which can be handled more easily if a modified, and in our opinion faster, line of reasoning is used.

We show that the terms overlooked by Josephy and Aczel [1993] approach zero as the number of observations approaches infinity. Therefore, we can prove that Josephy-Aczel's [1993] estimator is indeed asymptotically unbiased and mean squared error consistent.

Compared to the literature we can make two contributions. First and obviously, we identify and correct the mistake in [Josephy, Aczel 1993]. Second, in that way we allow researchers and practitioners in the
field of downside portfolio selection, hedging, downside asset pricing, risk measurement in a regulatory context, and performance measurement to work with a meaningfully specified downside measure, i.e. semivariance with mean as target, instead of making unfortunate compromises, i.e. using a constant as target when applying lower partial moment 2 or falling back to lower partial moment 1 when mean is used as target.

The remainder of the paper is organized as follows. In Section 2 the computational mistake in Josephy-Aczel's [1993] derivation is identified and in Section 3 it is corrected. The paper ends with a summary (Section $4)$ and a mathematical appendix.

## 2. Notations and identification of the computational mistake

## Notations

Since an immediate comparison to [Josephy, Aczel 1993] is essential for our paper, we use their notation:

Let $x_{1}, \ldots, x_{n}, \ldots$ denote a sequence of independent and identically distributed random variables with a finite fourth moment.

We define for $i=1, \ldots, n$ :

$$
\begin{equation*}
y_{i}:=x_{i}-\mu, \tag{1}
\end{equation*}
$$

where $\mu:=E\left\{x_{1}\right\}$.
When referring to aspects that hold for all $x_{i}\left(y_{i}\right)$, like the expected value or the variance, $x_{1}\left(y_{1}\right)$ is taken to represent all $x_{i}\left(y_{i}\right)$ because $x_{i}$ (and hence $y_{i}$ ) are independent and identically distributed random variables.

Given the definition of $y_{1}$, it is true

$$
\begin{gather*}
E\left\{y_{1}\right\}=0 \quad \sigma^{2}:=E\left\{y_{1}^{2}\right\}=\operatorname{var}\left(y_{1}\right)=\operatorname{var}\left(x_{1}\right)  \tag{2}\\
\bar{y}=\frac{1}{n} \cdot \sum_{i=1}^{n} y_{i}=\frac{1}{n} \cdot \sum_{i=1}^{n}\left(x_{i}-\mu\right)=\bar{x}-\mu, \tag{3}
\end{gather*}
$$

with

$$
\bar{x}:=\frac{1}{n} \cdot \sum_{i=1}^{n} x_{i} .
$$

Furthermore, we define
$m_{i}:=1_{(-\infty, 0]}\left(y_{i}\right)=1_{(-\infty, 0]}\left(x_{i}-\mu\right) \quad l_{i}:=1_{(0, \bar{y}]}\left(y_{i}\right)-1_{(\bar{y}, 0]}\left(y_{i}\right)$,
where $1_{A}(z)$ denotes the value of the indicator function on a set $A$ for variable $z$.

The value $m_{i}$ indicates when semivariance is "triggered" and $l_{i}$ captures "triggering errors". The estimator of semivariance is triggered based on the sample average $\bar{y}$ instead on the true mean $\mu$.

## Semivariance reads

$$
\begin{align*}
& \sigma_{-}^{2}:=E\left\{1_{(-\infty, 0]}\left(x_{1}-\mu\right) \cdot\left(x_{1}-\mu\right)^{2}\right\}=E\left\{1_{(-\infty, 0]}\left(y_{1}\right) \cdot y_{1}^{2}\right\}  \tag{5}\\
& =E\left\{m_{1} \cdot y_{1}^{2}\right\}
\end{align*}
$$

which suggests as reasonable estimator $t_{n}$

$$
\begin{align*}
& t_{n}:=c_{n} \sum_{i=1}^{n} 1_{(-\infty, 0]}\left(x_{i}-\bar{x}\right) \cdot\left(x_{i}-\bar{x}\right)^{2}=c_{n}  \tag{6}\\
& \sum_{i=1}^{n=1} 1_{(-\infty, 0]}\left(y_{i}-\bar{y}\right) \cdot\left(y_{i}-\bar{y}\right)^{2}
\end{align*}
$$

where the multiplier $c_{n} \in \mathbb{R}$ is yet to be determined.
Using the definitions of $m_{i}$ and $l_{i}$, Equation (6) simplifies to

$$
\begin{equation*}
t_{n}=c_{n} \cdot \sum_{i=1}^{n}\left[m_{i}+l_{i}\right] \cdot\left(y_{i}-\bar{y}\right)^{2} . \tag{7}
\end{equation*}
$$

Furthermore, set for $\tau=0,1,2, \ldots$

$$
\begin{equation*}
v_{\tau}:=E\left\{m_{1} \cdot\left(x_{1}-\mu\right)^{\tau}\right\}=E\left\{m_{1} \cdot y_{1}^{\tau}\right\}, \tag{8}
\end{equation*}
$$

where it obviously holds: $v_{2}=E\left\{m_{1} \cdot y_{1}^{2}\right\}=\sigma_{-}^{2}$ and $v_{0}$ can be interpreted as probability of $y_{1} \leq 0$, which corresponds to the probability of $x_{1} \leq \mu$.

### 2.1. Identification of the computational mistake in Josephy-Aczel's proof

To distinguish subsequently between "our" and "Josephy-Aczel's" formulas, we put JA in front of their formula numbers.

Josephy and Aczel claim

$$
E\left\{m_{i} \cdot y_{j} \cdot y_{k}\right\}=\left\{\begin{array}{cc}
E\left\{m_{i} \cdot y_{i}^{2}\right\}=\sigma_{-}^{2} & i=j=k  \tag{JA14}\\
0 & \text { otherwise }
\end{array}\right.
$$

While it is true, as Josephy and Aczel state, that $E\left\{m_{i} \cdot y_{j} \cdot y_{k}\right\}=0$ for $j \neq k$ due to the independence of $y_{j}$ and $y_{k}$ and the fact that $E\left\{y_{j}\right\}=$ $E\left\{y_{k}\right\}=0$, this is not true for $j=k \neq i$. For $j=k \neq i$ it holds

$$
\begin{equation*}
E\left\{m_{i} \cdot y_{j} \cdot y_{k}\right\}=E\left\{m_{i} \cdot y_{j}^{2}\right\}=v_{0} \cdot E\left\{y_{j}^{2}\right\}=v_{0} \cdot \sigma^{2} \tag{9}
\end{equation*}
$$

Term (9) is missing in Josephy-Aczel's [1993] proof of asymptotic unbiasedness and mean squared error consistency of their estimator, one mistake that leads subsequently to several wrong formulas.

Josephy-Aczel's [1993] proof of asymptotic unbiasedness is based on Formula (JA17). Since (JA17) rests upon (JA14), the term discovered in

Formula (9) is missing causing a follow-up error. The corrected formula (the notation "corr" is added to the numbering of the formulas) reads:

$$
\begin{equation*}
\mathrm{E}\left\{\frac{t_{n}}{c_{n}}\right\}=\underbrace{\frac{(n-1)^{2}}{n} \cdot \sigma_{-}^{2}+\sum_{i=1}^{n} E\left\{l_{i} \cdot\left(y_{i}-\bar{y}\right)^{2}\right\}}_{(J A 17)}+\frac{n-1}{n} \cdot \sigma^{2} \cdot v_{0} . \tag{corrJA17}
\end{equation*}
$$

Josephy-Aczel's [1993] proof of mean squared error consistency is based on their Formulas (JA20a) through (JA21f), which ultimately partially rely on (JA14). For that reason, only (JA20b), (JA21a), and (JA21b) are correct.

- Formula (corrJA20a)
(JA20a) contains a typo and reads corrected (Josephy and Aczel [1993] obtain $v_{2}^{2}$ ):

$$
\begin{equation*}
E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{j}\right\}=v_{1}^{2} \text { for } i \neq j . \tag{corrJA20a}
\end{equation*}
$$

All other formulas are subject to the follow-up error as the term discovered in Formula (9) is missing. The corrected formulas read (where $i \neq j$ ):

- Formula (corrJA20c)

$$
\begin{gather*}
E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{j} \cdot \bar{y}^{2}\right\}= \\
\underbrace{\frac{2}{n^{2}} \cdot\left(v_{1} \cdot v_{3}+v_{2}^{2}\right)}_{(J A 20 c)}+\frac{n-2}{n^{2}} \cdot v_{1}^{2} \cdot \sigma^{2} \tag{corrJA20c}
\end{gather*}
$$

- Formula (corrJA20d)

$$
\begin{gathered}
E\left\{m_{i} \cdot m_{j} \cdot\left(y_{i}+y_{j}\right)^{2} \cdot \bar{y}^{2}\right\}= \\
\underbrace{\frac{2}{n^{2}} \cdot\left(v_{0} \cdot v_{4}+4 \cdot v_{1} \cdot v_{3}+3 \cdot v_{2}^{2}\right)}_{(J A 20 d)}+ \\
2 \cdot \frac{n-2}{n^{2}} \cdot\left[v_{0} \cdot v_{2} \cdot \sigma^{2}+v_{1}^{2} \cdot \sigma^{2}\right] .
\end{gathered}
$$

- Formula (corrJA20e)

$$
\begin{gathered}
E\left\{m_{i} \cdot m_{j} \cdot\left(y_{i}+y_{j}\right) \cdot \bar{y}^{3}\right\}= \\
\underbrace{\frac{2}{n^{3}} \cdot\left(v_{0} \cdot v_{4}+4 \cdot v_{1} \cdot v_{3}+3 \cdot v_{2}^{2}\right)}_{(J A 20 e)}+
\end{gathered}
$$

(corrJA20e)

$$
2 \cdot \frac{n-2}{n^{3}} \cdot\left[3 \cdot v_{0} \cdot v_{2} \cdot \sigma^{2}+3 \cdot v_{1}^{2} \cdot \sigma^{2}+v_{0} \cdot v_{1} \cdot E\left\{y_{1}^{3}\right\}\right]
$$

- Formula (corrJA20f)

$$
\begin{gather*}
E\left\{m_{i} \cdot m_{j} \cdot \bar{y}^{4}\right\}=\underbrace{\frac{2}{n^{4}} \cdot\left(v_{0} \cdot v_{4}+4 \cdot v_{1} \cdot v_{3}+3 \cdot v_{2}^{2}\right)}_{(J A 20 f)}+ \\
2 \cdot \frac{n-2}{n^{4}} \cdot\left[\frac{1}{2} \cdot v_{0}^{2} \cdot E\left\{y_{1}^{4}\right\}+4 \cdot v_{0} \cdot v_{1} \cdot E\left\{y_{1}^{3}\right\}\right.  \tag{corrJA20f}\\
\left.+6 \cdot v_{2} \cdot \sigma^{2}+\frac{3}{2} \cdot(n-3) \cdot v_{0}^{2} \cdot \sigma^{4}+6 \cdot v_{1}^{2} \cdot \sigma^{2}\right] .
\end{gather*}
$$

- Formula (corrJA21c)

$$
\begin{equation*}
E\left\{m_{i} \cdot y_{i}^{2} \cdot \bar{y}^{2}\right\}=\underbrace{\frac{v_{4}}{n^{2}}}_{\left(J A^{2} 1 c\right)}+\frac{(n-1) \cdot v_{2} \cdot \sigma^{2}}{n^{2}} . \tag{corrJA21c}
\end{equation*}
$$

- Formula (corrJA21d)

$$
\begin{align*}
E\left\{m_{i} \cdot y_{i} \cdot \bar{y}^{3}\right\}= & \underset{\substack{(J A 21 d) \\
\frac{v_{4}}{n^{3}}}}{ }+\frac{n-1}{n^{3}} \cdot\left[v_{1} \cdot E\left\{y_{1}^{3}\right\}+\right.  \tag{corrJA21d}\\
& \left.3 \cdot v_{2} \cdot \sigma^{2}\right] .
\end{align*}
$$

- Formula (corrJA21e)

$$
\begin{align*}
& E\left\{m_{i} \cdot \bar{y}^{4}\right\}=\underset{(J A 21 e)}{\frac{v_{4}}{n^{4}}}+\frac{n-1}{n^{4}} \cdot\left[v_{0} \cdot E\left\{y_{1}^{4}\right\}+4 .\right. \\
& \left.v_{1} \cdot E\left\{y_{1}^{3}\right\}+6 \cdot v_{2} \cdot \sigma^{2}+3 \cdot(n-2) \cdot v_{0} \cdot \sigma^{4}\right] . \tag{corrJA21e}
\end{align*}
$$

- Formula (corrJA21f)

$$
\begin{equation*}
E\left\{m_{i} \cdot\left(y_{i}-\bar{y}\right)^{2}\right\}=\underbrace{\frac{(n-1)^{2}}{n^{2}} \cdot v_{2}}_{(J A 21 f)}+\frac{n-1}{n^{2}} \cdot v_{0} \cdot \sigma^{2} . \tag{corrJA21f}
\end{equation*}
$$

One exemplary proof, namely the derivation of Formula (corrJA20e), can be found in Appendix 1. The other corrected formulas can be derived in a similar way.

## 3. Correction of the proof

To compute asymptotic unbiasedness and mean squared error consistency, we deviate from Josephy-Aczel's [1993] original proof. The missing term (9) can be handled easier if a modified and in our opinion faster line of reasoning is used.

### 3.1. Useful relations, lemmas, and a corollary

This subsection contains one relation, two lemmas, and one corollary that will help simplify the proofs in Subsections 3.2 and 3.3.

## Relation

For $i=1, \cdots, n$ it holds

$$
\begin{equation*}
m_{i}^{2}=m_{i} \text { and }\left(m_{i}+l_{i}\right)^{2}=m_{i}+l_{i} \tag{10}
\end{equation*}
$$

since $m_{i}$ and $m_{i}+l_{i}=1_{(-\infty, \bar{y}]}\left(y_{i}\right)$ are indicator functions.

## Lemma 1

For $k \in \mathbb{N}$ and $i=1, \cdots, n$ it holds

$$
\begin{gather*}
\left|l_{i}\right| \cdot\left|y_{i}-\bar{y}\right|^{k}=\left|1_{(0, \bar{y}]}\left(y_{i}\right)-1_{(\bar{y}, 0]}\left(y_{i}\right)\right| \cdot\left|y_{i}-\bar{y}\right|^{k} \leq \\
|\bar{y}|^{k}=|\bar{x}-\mu|^{k} . \tag{11}
\end{gather*}
$$

For the proof of (11) observe: $\left|l_{i}\right|=1$ if $y_{i}$ lies between 0 and $\bar{y}$ irrespective of which of either value is less. In this case, the distance between $y_{i}$ and $\bar{y}$ is not greater than $|0-\bar{y}|=|\bar{y}|$ since $|0-\bar{y}|$ is the maximum possible distance. If otherwise $y_{i}$ does not lie between 0 and $\bar{y}$, $1_{(0, \bar{y}]}\left(y_{i}\right)-1_{(\bar{y}, 0]}\left(y_{i}\right)$ will be zero and so will $\left|l_{i}\right|$.

Lemma 2 (see Appendix 2.1 for a proof)
Let $y_{1}, \ldots, y_{n}, \ldots$ denote a sequence of independent and identically distributed random variables with existing mean $E\left\{y_{1}\right\}=0$ and with finite $k^{\text {th }}$ moment $E\left\{y_{1}{ }^{k}\right\}$ for some $k \in \mathbb{N}$.

Then for all $\kappa=1, . ., k$ the expected value $E\left\{\bar{y}^{\kappa}\right\}$ exists and it holds

$$
\begin{equation*}
E\left\{\bar{y}^{\kappa}\right\} \rightarrow 0 \text { for } n \rightarrow \infty . \tag{12}
\end{equation*}
$$

Corollary (see Appendix 2.2 for a proof)
Let $y_{1}, \ldots, y_{n}, \ldots$ denote a sequence of independent and identically distributed random variables with existing mean $E\left\{y_{1}\right\}=0$. If for $k \in \mathbb{N}$ the expected value $E\left\{y_{1}{ }^{k}\right\}$ exists for $k$ even and $E\left\{y_{1}{ }^{k+1}\right\}$ exists for $k$ odd, $E\left\{|\bar{y}|^{k}\right\}$ exists as well and it holds

$$
\begin{equation*}
E\left\{\left|\bar{y}^{k}\right|\right\} \rightarrow 0 \text { for } n \rightarrow \infty . \tag{13}
\end{equation*}
$$

Note that the existence of $E\left\{y_{1}{ }^{k+1}\right\}$ for $k$ odd is required only for the proof of convergence, but not for the proof of existence of $E\left\{y_{1}{ }^{k}\right\}$.

### 3.2. Proof of asymptotic unbiasedness

$$
E\left\{t_{n}\right\}=c_{n} \cdot E\left\{\sum_{i=1}^{n}\left[m_{i}+l_{i}\right] \cdot\left(y_{i}-\bar{y}\right)^{2}\right\}
$$

can be re-written as

$$
\begin{gathered}
E\left\{t_{n}\right\}=c_{n} \cdot E\left\{\sum _ { i = 1 } ^ { n } \left[m_{i} \cdot y_{i}^{2}-2 \cdot m_{i} \cdot y_{i} \cdot \bar{y}+m_{i} \cdot \bar{y}^{2}+l_{i} .\right.\right. \\
\left.\left.\left(y_{i}-\bar{y}\right)^{2}\right]\right\}=n \cdot c_{n} \cdot[\sigma_{-}^{2}-2 \cdot \underbrace{E\left\{m_{1} \cdot y_{1} \cdot \bar{y}\right\}}_{=: A_{n}}+\underbrace{E\left\{m_{1} \cdot \bar{y}^{2}\right\}}_{=: B_{n}}+ \\
\underbrace{E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{2}\right\}}_{=: c_{n}}],
\end{gathered}
$$

because $y_{1}, \ldots, y_{n}$ are independent and identically distributed and $E\left\{m_{1} \cdot y_{1}^{2}\right\} \underset{\sim}{\sigma_{-}^{2}}$.
(5)

To prove asymptotic unbiasedness, we will show that $A_{n}, B_{n}$, and $C_{n}$ converge to 0 for $n \rightarrow \infty$. Since null sequences are considered, it suffices to show that $\left|A_{n}\right|,\left|B_{n}\right|=B_{n}$, and $\left|C_{n}\right|$ converge to 0 for $n \rightarrow \infty$.

Then asymptotic unbiasedness will hold if $c_{n}$ is chosen in a way such that $n \cdot c_{n}$ converges to 1 for $n \rightarrow \infty$ :

- $A_{n}$

$$
\begin{aligned}
& 0 \leq\left|A_{n}\right|=\left|E\left\{m_{1} \cdot y_{1} \cdot \bar{y}\right\}\right|=\left|E\left\{\frac{1}{n} \cdot m_{1} \cdot y_{1} \cdot\left(y_{1}+\sum_{i=2}^{n} y_{i}\right)\right\}\right|= \\
& \frac{1}{n} \cdot\left|E\left\{m_{1} \cdot y_{1}^{2}\right\}+\sum_{i=2}^{n} E\left\{m_{1} \cdot y_{1} \cdot y_{i}\right\}\right| \underset{(2)}{=\frac{1}{n}} \cdot E\left\{m_{1} \cdot y_{1}^{2}\right\} \underset{(5)}{=} \frac{\sigma_{-}^{2}}{n} \rightarrow 0
\end{aligned}
$$

for $n \rightarrow \infty$.

- $B_{n}$

$$
0 \leq\left|B_{n}\right|=B_{n}=E\left\{m_{1} \cdot \bar{y}^{2}\right\} \leq E\left\{\bar{y}^{2}\right\} \underbrace{\rightarrow 0}_{\text {Lemma } 2} \text { for } n \rightarrow \infty .
$$

- $C_{n}$

$$
\left|E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{2}\right\}\right| \varliminf_{(\#)}^{0 \leq\left|C_{n}\right|} E\left\{\left|l_{1}\right| \cdot\left|y_{1}-\bar{y}\right|^{2}\right\} \underset{\text { Lemma } 1}{\vdots} E\left\{|\bar{y}|^{2}\right\} \underset{\text { Corollary }}{\rightarrow 0} \text { for }
$$

Inequality (\#) rests upon the well-known relation $|E\{X\}| \leq E\{|X|\}$.

- $n \cdot c_{n}$

Asymptotic unbiasedness is obtained if $c_{n}$ is selected in a way such that $n \cdot c_{n}$ converges to 1 for $n \rightarrow \infty$. This means, a multiplier $c_{n}=\frac{1}{n} \cdot a_{n}$ can be chosen for any $a_{n}$ with $a_{n} \rightarrow 1$ for $n \rightarrow \infty$. Special cases for $c_{n}\left(a_{n}\right)$ include $c_{n}=\frac{1}{n}\left(a_{n}=1\right), c_{n}=\frac{1}{n-1}\left(a_{n}=\frac{n}{n-1}\right)$, Josephy-Aczel's [1993]
recommendation $c_{n}=\frac{n}{(n-1)^{2}}\left(a_{n}=\frac{n^{2}}{(n-1)^{2}}\right)$ or $c_{n}=\frac{1}{n-k}$ for any $k \in \mathbb{Z}$ and $n>k\left(a_{n}=\frac{n}{n-k}\right)$.
Observe that $c_{n} \rightarrow 0$ for $n \rightarrow \infty$ if $n \cdot c_{n} \rightarrow 1$.

### 3.3. Proof of mean squared error consistency

Since the fourth moment $E\left\{y_{1}^{4}\right\}$ was assumed to exist, the mean squared error of $t_{n}$ exists and can be written:

$$
\operatorname{mse}\left(t_{n}\right)=\operatorname{var}\left(t_{n}\right)+\left(\operatorname{bias}\left(t_{n}\right)\right)^{2}=E\left\{t_{n}^{2}\right\}-\left(E\left\{t_{n}\right\}\right)^{2}+\left(\operatorname{bias}\left(t_{n}\right)\right)^{2} .
$$

However, it is already known that the estimator is asymptotically unbiased so that it holds

$$
\begin{gathered}
E\left\{t_{n}\right\} \rightarrow \sigma_{-}^{2} \text { for } n \rightarrow \infty \\
\left(E\left\{t_{n}\right\}\right)^{2} \rightarrow \sigma_{-}^{4} \text { for } n \rightarrow \infty \\
\operatorname{bias}\left(t_{n}\right) \rightarrow 0 \text { for } n \rightarrow \infty \\
\left(\operatorname{bias}\left(t_{n}\right)\right)^{2} \rightarrow 0 \text { for } n \rightarrow \infty
\end{gathered}
$$

hence it remains to show that $E\left\{t_{n}{ }^{2}\right\} \rightarrow \sigma_{-}^{4}$ for $n \rightarrow \infty$.
To that end, we consider

$$
\begin{gather*}
E\left\{t_{n}{ }^{2}\right\}=E\left\{\left(c_{n} \cdot \sum_{i=1}^{n}\left(m_{i}+l_{i}\right) \cdot\left(y_{i}-\bar{y}\right)^{2}\right)^{2}\right\}= \\
c_{n}{ }^{2} \cdot E\left\{\sum_{i=1}^{n} \sum_{j=1}^{n}\left(m_{i}+l_{i}\right) \cdot\left(m_{j}+l_{j}\right) \cdot\left(y_{i}-\bar{y}\right)^{2} \cdot\left(y_{j}-\bar{y}\right)^{2}\right\}= \\
c_{n}{ }^{2} \cdot E\left\{\sum_{i=1}^{n}\left(m_{i}+l_{i}\right)^{2} \cdot\left(y_{i}-\bar{y}\right)^{4}\right\}+  \tag{14}\\
c_{n}{ }^{2} \cdot E\left\{\sum_{i=1}^{n} \sum_{\substack{j=1 \\
j \neq i}}^{n}\left(m_{i}+l_{i}\right) \cdot\left(m_{j}+l_{j}\right) \cdot\left(y_{i}-\bar{y}\right)^{2} \cdot\left(y_{j}-\bar{y}\right)^{2}\right\} \underset{i i d,(10)}{=}
\end{gather*}
$$

$$
n \cdot(n-1) \cdot c_{n}{ }^{2} \cdot \underbrace{E\left\{\left(m_{1}+l_{1}\right) \cdot\left(m_{2}+l_{2}\right) \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}}_{=: F_{n}} .
$$

It is shown in Appendix 3.1 that $n \cdot c_{n}{ }^{2} \cdot D_{n}$ converges to 0 for $n \rightarrow \infty$ and $n \cdot(n-1) \cdot c_{n}{ }^{2} \cdot F_{n}$ converges to $\sigma_{-}^{4}$ (see Appendix 3.2) why

$$
E\left\{t_{n}^{2}\right\} \rightarrow \sigma_{-}^{4} \text { for } n \rightarrow \infty
$$

holds and mean squared error consistency of the estimator $t_{n}$ is proven.

## 4. Summary

The starting point for our paper is the observation that semivariance is applied in downside portfolio selection, hedging, downside asset pricing, risk measurement in a regulatory context, and performance measurement. To successfully use semivariance in practice, a statistical estimator of semivariance is needed.

If mean is used as target for semivariance, only the vastly underappreciated paper by Josephy and Aczel [1993] provides a statistical estimator for semivariance. Unfortunately, Josephy and Aczel [1993] have not correctly proven asymptotic unbiasedness and mean squared error consistency of their estimator. In their proof, they mistakenly assume terms to be 0 that are in fact unequal to 0 .

This paper corrects the computational mistake in Josephy and Aczel's [1993 original proof of asymptotic unbiasedness and mean squared error consistency. It shows that the terms overlooked by Josephy and Aczel [1993] approach zero as the number of observations approaches infinity. Therefore, we prove that Josephy and Aczel's [1993] estimator is indeed asymptotically unbiased and mean squared error consistent.

In that way, the paper allows researchers and practitioners in the field of downside portfolio selection, hedging, downside asset pricing, risk measurement in a regulatory context, and performance measurement to work with a meaningfully specified downside measure, i.e. semivariance with mean as target, instead of making unfortunate compromises, i.e. using a constant as target when applying lower partial moment 2 or falling back to lower partial moment 1 when mean is used as target.

## Appendix 1. Proof of formula (corrJA20e)

$$
\begin{gathered}
E\left\{m_{i} \cdot m_{j} \cdot\left(y_{i}+y_{j}\right) \cdot \bar{y}^{3}\right\}=E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}+E\left\{m_{i} \cdot m_{j} \cdot y_{j} \cdot \bar{y}^{3}\right\}= \\
2 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}
\end{gathered}
$$

Since

$$
\begin{gathered}
\bar{y}^{3}=\frac{1}{n^{3}} \cdot \sum_{r=1}^{n} \sum_{s=1}^{n} \sum_{t=1}^{n} y_{r} \cdot y_{s} \cdot y_{t}= \\
\frac{1}{n^{3}} \cdot\left(\sum_{r=1}^{n} y_{r}^{3}+3 \cdot \sum_{\substack{r=1}}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} y_{r}^{2} \cdot y_{s}+\sum_{\substack{r=1}}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} \sum_{\substack{t=1 \\
t \neq r, s}}^{n} y_{r} \cdot y_{s} \cdot y_{t}\right)
\end{gathered}
$$

it is obtained for

$$
\begin{aligned}
& E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}=\frac{1}{n^{3}} . \\
& E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \sum_{r=1}^{n} y_{r}^{3}+m_{i} \cdot m_{j} \cdot y_{i} \cdot 3 \cdot \sum_{r=1}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} y_{r}^{2} \cdot y_{s}+m_{i} \cdot m_{j} \cdot y_{i}\right. \\
& \left.\cdot \sum_{r=1}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} \sum_{\substack{t=1 \\
t \neq r, s}}^{n} y_{r} \cdot y_{s} \cdot y_{t}\right\}= \\
& \frac{1}{n^{3}} \cdot\left[E\left\{m_{i} \cdot m_{j} \cdot y_{i}^{4}\right\}+E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{j}^{3}\right\}+E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} y_{r}^{3}\right\}+\right. \\
& 3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i}^{3} \cdot y_{j}\right\}+3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i}^{3} \cdot \sum_{\substack{s=1 \\
s \neq i, j}}^{n} y_{s}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i}^{2} \cdot y_{j}^{2}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{j}^{2} \cdot \sum_{\substack{s=1 \\
s \neq i, j}}^{n} y_{s}\right\}+3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i}^{2} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} y_{r}^{2}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{j} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} y_{r}^{2}\right\}+3 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} \sum_{\substack{s=1 \\
s \neq r, i, j}}^{n} y_{r}^{2} \cdot y_{s}\right\}+
\end{aligned}
$$

$$
\begin{aligned}
& \left.E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \sum_{r=1}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} \sum_{t=1}^{n \neq r, s}<1 y_{r} \cdot y_{s} \cdot y_{t}\right\}\right] \\
& \underset{\text { independence }}{=} \frac{1}{n^{3}} \cdot\left[E\left\{m_{i} \cdot y_{i}^{4}\right\} \cdot E\left\{m_{j}\right\}+E\left\{m_{i} \cdot y_{i}\right\} \cdot E\left\{m_{j} \cdot y_{j}^{3}\right\}+\right. \\
& E\left\{m_{i} \cdot y_{i}\right\} \cdot E\left\{m_{j}\right\} \cdot E \sum_{\substack{r=1 \\
r \neq i, j}}^{n}\left\{y_{r}^{3}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot y_{i}^{3}\right\} \cdot E\left\{m_{j} \cdot y_{j}\right\}+3 \cdot E\left\{m_{i} \cdot y_{i}^{3}\right\} \cdot E\left\{m_{j}\right\} \cdot \sum_{\substack{s=1 \\
s \neq i, j}}^{n} E\left\{y_{s}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot y_{i}^{2}\right\} \cdot E\left\{m_{j} \cdot y_{j}^{2}\right\}+ \\
& 3 \cdot E\left\{m_{i} \cdot y_{i}\right\} \cdot E\left\{m_{j} \cdot y_{j}^{2}\right\} \cdot \sum_{\substack{s=1 \\
s \neq i, j}}^{n} E\left\{y_{s}\right\}+3 \cdot E\left\{m_{i} \cdot y_{i}^{2}\right\} \cdot E\left\{m_{j}\right\} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} E\left\{y_{r}^{2}\right\} \\
& +3 \cdot E\left\{m_{i} \cdot y_{i}\right\} \cdot E\left\{m_{j} \cdot y_{j}\right\} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} E\left\{y_{r}^{2}\right\} \\
& +3 \cdot E\left\{m_{i} \cdot y_{i}\right\} \cdot E\left\{m_{j}\right\} \cdot \sum_{\substack{r=1 \\
r \neq i, j}}^{n} E\left\{y_{r}^{2}\right\} \cdot \sum_{\substack{s=1 \\
s \neq r, i, j}}^{n} E\left\{y_{s}\right\} \\
& +\sum_{r=1}^{n} \sum_{\substack{s=1 \\
s \neq r}}^{n} \sum_{t=1}^{n} E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{r} \cdot y_{s} \cdot y_{t}\right\} .
\end{aligned}
$$

Given the definition of $v_{\tau}$ in (8), the fact that $y_{1}, \ldots, y_{n}, \ldots$ are independent and identically distributed, and $E\left\{y_{1}\right\}=0$ (see (2)), it is gained for

$$
\begin{gathered}
E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}=\frac{1}{n^{3}} \cdot\left[v_{4} \cdot v_{0}+v_{1} \cdot v_{3}+v_{1} \cdot v_{0} \cdot(n-2) \cdot E\left\{y_{1}^{3}\right\}+\right. \\
3 \cdot v_{3} \cdot v_{1}+3 \cdot v_{3} \cdot v_{0} \cdot 0+ \\
3 \cdot v_{2} \cdot v_{2}+3 \cdot v_{1} \cdot v_{2} \cdot 0+3 \cdot v_{2} \cdot v_{0} \cdot(n-2) \cdot \sigma^{2}+ \\
\left.3 \cdot v_{1}^{2} \cdot(n-2) \cdot \sigma^{2}+3 \cdot v_{1} \cdot v_{0} \cdot(n-2) \cdot \sigma^{2} \cdot 0+0\right] .
\end{gathered}
$$

To understand the zero in the last term of the above formula, note that by construction, $r, s$, and $t$ never possess identical values. Moreover, at least one of these subscripts is in addition different from $i$ and $j$. Hence, $E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot y_{r} \cdot y_{s} \cdot y_{t}\right\}$ is a linear function of $E\left\{y_{1}\right\}$.

This finally yields

$$
\begin{gathered}
E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}=\frac{1}{n^{3}} \cdot\left[v_{4} \cdot v_{0}+4 \cdot v_{1} \cdot v_{3}+3 \cdot v_{2}^{2}\right] \\
\frac{n-2}{n^{3}} \cdot\left[3 \cdot v_{2} \cdot v_{0} \cdot \sigma^{2}+3 \cdot v_{1}^{2} \cdot \sigma^{2}+v_{1} \cdot v_{0} \cdot E\left\{y_{1}^{3}\right\}\right] .
\end{gathered}
$$

Note that $E\left\{m_{i} \cdot m_{j} \cdot\left(y_{i}+y_{j}\right) \cdot \bar{y}^{3}\right\}=2 \cdot E\left\{m_{i} \cdot m_{j} \cdot y_{i} \cdot \bar{y}^{3}\right\}$ to see the equivalence to (corrJA20e).

## Appendix 2. Proof of lemma 2 and the corollary

## Appendix 2.1. Proof of lemma 2

## Lemma 2

Let $y_{1}, \ldots, y_{n}, \ldots$ denote a sequence of independent and identically distributed random variables with existing mean $E\left\{y_{1}\right\}=0$ and with finite $k^{\text {th }}$ moment $E\left\{y_{1}{ }^{k}\right\}$ for some $k \in \mathbb{N}$.

Then for all $\kappa=1, . ., k$ the expected value $E\left\{\bar{y}^{\kappa}\right\}$ exists and it holds

$$
\begin{equation*}
E\left\{\bar{y}^{\kappa}\right\} \rightarrow 0 \text { for } n \rightarrow \infty . \tag{12}
\end{equation*}
$$

## Proof

First step: existence of $E\left\{\bar{y}^{\kappa}\right\}$
Note that an existing $k^{\text {th }}$ moment $E\left\{y_{1}{ }^{k}\right\}$ implies that the $1^{\text {st }}, 2^{\text {nd }}, \ldots$, $k-1^{\text {th }}$ moments exist as well. Using the multinomial theorem (see e.g. [Kotz, Johnson 1985]), $\bar{y}^{\kappa}$ can be written as

$$
\bar{y}^{\kappa}=\left(\frac{y_{1}+\cdots+y_{n}}{n}\right)^{\kappa}=\frac{1}{n^{\kappa}} . \sum_{k_{1}+k_{2}+. .+k_{n}=\kappa}\binom{\kappa}{k_{1}, k_{2}, \ldots, k_{n}} \prod_{i=1}^{n} y_{i}^{k_{i}},
$$

where $\binom{\kappa}{k_{1}, k_{2}, \ldots, k_{n}}=\frac{\kappa!}{\prod_{i=1}^{n} k_{i}!}$ denotes the multinomial coefficient.
Since all expected values $E\left\{y_{i}^{k_{i}}\right\}$ on the right hand side exist, the expected value of $\bar{y}^{\kappa}$ exists as well.
Second step: proving (12) by induction
Base case: $\kappa=1$

$$
E\{\bar{y}\}=\frac{1}{n} \cdot E\left\{\sum_{i=1}^{n} y_{i}\right\}=\frac{1}{n} \cdot \sum_{i=1}^{n} E\left\{y_{i}\right\}{\underset{i i d}{i d}}_{\left.\frac{1}{n} \cdot n \cdot 0=0 \rightarrow 0 \text { for } n \rightarrow \infty\right)}
$$

Inductive step: We assume $E\left\{\bar{y}^{\vartheta}\right\} \rightarrow 0$ for $n \rightarrow \infty$ for all $\vartheta=1, \ldots, \kappa-$ $1<k$. We have to show that

$$
E\left\{\bar{y}^{\kappa}\right\} \rightarrow 0 \text { for } n \rightarrow \infty
$$

is also true.

$$
\begin{aligned}
& E\left\{\bar{y}^{\kappa}\right\}=\frac{1}{n^{\kappa}} \cdot E\left\{\left(\sum_{i=1}^{n} y_{i}\right) \cdot\left(\sum_{j=1}^{n} y_{j}\right)^{\kappa-1}\right\} \underset{\text { independence }}{=} \\
& \frac{1}{n^{\kappa}} \cdot \sum_{i=1}^{n} E\left\{y_{i} \cdot\left(\sum_{j=1}^{n} y_{j}\right)^{\kappa-1}\right\}=\frac{1}{n^{\kappa}} \cdot \sum_{i=1}^{n} E\left\{y_{i} \cdot\left(y_{i}+\sum_{\substack{j=1 \\
j \neq i}}^{n} y_{j}\right)^{\kappa-1}\right\} \\
& {\underset{\text { binomial theorem }}{=}}_{\sum_{n}^{\kappa}} \cdot \sum_{i=1}^{n}\left(\sum_{l=0}^{\kappa-1}\binom{\kappa-1}{l} \cdot E\left\{y_{i}^{l+1} \cdot\left(\sum_{\substack{j=1 \\
j \neq i}}^{n} y_{j}\right)\right\}\right) \\
& \underset{\text { independence }}{=} \frac{1}{n^{\kappa}} \cdot n \cdot \sum_{l=0}^{\kappa-1}\binom{\kappa-1}{l} \cdot E\left\{y_{1}^{l+1}\right\} \cdot E\left\{\left(\sum_{\substack{j=1 \\
j \neq 1}}^{n} y_{j}\right)^{\kappa-1-l}\right\} \\
& \underset{E\left\{y_{1}\right\}=0}{=} \frac{(n-1)^{\kappa-1}}{n^{\kappa-1}} \\
& \cdot \sum_{l=1}^{\kappa-1}\binom{\kappa-1}{l} \cdot E\left\{y_{1}^{l+1}\right\} \cdot \frac{1}{(n-1)^{l}} \cdot E\left\{\left(\frac{1}{n-1} \cdot \sum_{j=2}^{n} y_{j}\right)^{\kappa-1-l}\right\}
\end{aligned}
$$

It holds for $n \rightarrow \infty: \frac{(n-1)^{\kappa-1}}{n^{\kappa-1}}=\left(1-\frac{1}{n}\right)^{\kappa-1} \rightarrow 1, E\left\{y_{1}^{l+1}\right\}$ is by assumption finite, and $\frac{1}{(n-1)^{l}} \rightarrow 0$ for $l \geq 1$. Moreover, $E\left\{\left(\frac{1}{n-1}\right.\right.$. $\left.\left.\sum_{j=2}^{n} y_{j}\right)^{\kappa-1-l}\right\}$ exhibits the same convergence behavior as $E\left\{\bar{y}^{\kappa-1-l}\right\}=$ $E\left\{\left(\frac{1}{n} \cdot \sum_{j=1}^{n} y_{j}\right)^{\kappa-1-l}\right\}$. The term $E\left\{\left(\frac{1}{n} \cdot \sum_{j=1}^{n} y_{j}\right)^{\kappa-1-l}\right\}$, however, converges to 0 for $n \rightarrow \infty$ and $l<\kappa-1$ due to the inductive assumption; for $l=\kappa-1$ this term reads $E\left\{\left(\frac{1}{n} \cdot \sum_{j=1}^{n} y_{j}\right)^{0}\right\}=1$. Putting all the above statements together, it leads to: $E\left\{\bar{y}^{\kappa}\right\}$ converges to 0 for $n \rightarrow \infty$.

## Appendix 2.2. Proof of the corollary

## Corollary

Let $y_{1}, \ldots, y_{n}, \ldots$ denote a sequence of independent and identically distributed random variables with existing mean $E\left\{y_{1}\right\}=0$. If for $k \in \mathbb{N}$ the expected value $E\left\{y_{1}{ }^{k}\right\}$ exists for $k$ even and $E\left\{y_{1}{ }^{k+1}\right\}$ exists for $k$ odd, $E\left\{|\bar{y}|^{k}\right\}$ exists as well and it holds

$$
\begin{equation*}
E\left\{\left|\bar{y}^{k}\right|\right\} \rightarrow 0 \text { for } n \rightarrow \infty . \tag{10}
\end{equation*}
$$

## Proof

First case: $k$ is even, i.e. $k=2 \cdot \varphi$ for some $\varphi \in \mathbb{N}$.
Then it holds

$$
E\left\{\left|\bar{y}^{k}\right|\right\}=E\left\{\bar{y}^{k}\right\} \underset{\text { Lemma } 2}{\vec{~}} 0 \text { for } n \rightarrow \infty .
$$

Second case: $k$ is odd, i.e. $k=2 \cdot \varphi+1=\varphi+\varphi+1$ for some $\varphi \in \mathbb{N}_{0}$. Then it is true for $k=1$ (which means $\varphi=0$ )

$$
0 \leq E\left\{1 \cdot\left|\bar{y}^{1}\right|\right\} \underset{\begin{array}{c}
\text { Cauchy-Schwarz } \\
\text { inequality }
\end{array}}{\vdots} \sqrt{E\left\{1^{2}\right\} \cdot E\left\{\bar{y}^{2}\right\}}=\sqrt{\underbrace{E\left\{\bar{y}^{2}\right\}}_{\text {Lemma }}} \rightarrow 0 \text { for } n \rightarrow \infty
$$

For $k>1$, i.e. $\varphi \in \mathbb{N}$, it is obtained

$$
\begin{aligned}
& 0 \leq E\left\{\left|\bar{y}^{k}\right|\right\}=E\left\{|\bar{y}|^{\varphi} \cdot|\bar{y}|^{\varphi+1}\right\} \underset{\begin{array}{c}
\text { Cauchy-Schwarz } \\
\text { inequality }
\end{array}}{\vdots} \sqrt{E\left\{\bar{y}^{2 \cdot \varphi}\right\} \cdot E\left\{\bar{y}^{2 \cdot \varphi+2}\right\}} \\
& =\sqrt{\underbrace{E\left\{\bar{y}^{k-1}\right\}}_{\text {Lemma } 2} \cdot \underbrace{G\left\{\bar{y}^{k+1}\right\}}_{\text {Lemma } 2}} \rightarrow 0 \text { for } n \rightarrow \infty \text {. }
\end{aligned}
$$

## Appendix 3. Proofs in the context of mean squared error consistency

Appendix 3.1. Analysis of $\boldsymbol{n} \cdot \boldsymbol{c}_{\boldsymbol{n}}{ }^{2} \cdot \boldsymbol{D}_{\boldsymbol{n}}$ from Formula (14)

$$
D_{n}=E\left\{\left(m_{1}+l_{1}\right) \cdot\left(y_{1}-\bar{y}\right)^{4}\right\}=E\left\{m_{1} \cdot\left(y_{1}-\bar{y}\right)^{4}\right\}+E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{4}\right\} .
$$

Applying the binomial theorem to $\left(y_{1}-\bar{y}\right)^{4}$ leads to
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$$
D_{n}=\sum_{i=0}^{4}\binom{4}{i} \cdot \underbrace{E\left\{m_{1} \cdot y_{1}^{i} \cdot \bar{y}^{4-i}\right\}}_{=: G_{i, n}}+\underbrace{E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{4}\right\}}_{=: H_{n}}
$$

$\underline{\text { Terms } G_{i, n}}$

- $G_{4, n}$ :

$$
0 \leq\left|G_{4, n}\right|=G_{4, n}=E\left\{m_{1} \cdot y_{1}^{4}\right\} \leq E\left\{y_{1}^{4}\right\}
$$

Hence, $G_{4, n}$ is bounded since $E\left\{y_{1}^{4}\right\}$ is, by assumption, finite.

- $G_{0, n}$ :

$$
0 \leq\left|G_{0, n}\right|=G_{0, n}=E\left\{m_{1} \cdot \bar{y}^{4}\right\} \leq E\left\{\bar{y}^{4}\right\} \underset{\text { Lemma } 2}{\longrightarrow} 0 \text { for } n \rightarrow \infty
$$

- $G_{2, n}$ :

$$
\begin{gathered}
0 \leq\left|G_{2, n}\right|=G_{2, n}= \\
E\left\{m_{1} \cdot y_{1}^{2} \cdot \bar{y}^{2}\right\} \underset{\begin{array}{c}
\text { Cauchy-Schwarz } \\
\text { inequality }
\end{array}}{\underbrace{E\left\{m_{1}^{2} \cdot y_{1}^{4}\right\}}_{=E\left\{m_{1} \cdot y_{1}^{4}\right\}=G_{4, n}} \cdot \underbrace{E\left\{\bar{y}^{4}\right\}}_{\begin{array}{c}
\text { Lemma } 2
\end{array}}} \rightarrow 0
\end{gathered}
$$

for $n \rightarrow \infty$

- $G_{1, n}$ :

$$
\left|E\left\{m_{1} \cdot y_{1} \cdot \bar{y}^{3}\right\}\right| \begin{gathered}
\begin{array}{c}
\text { Cauchy-Schwarz } \\
\text { inequality }
\end{array} \\
\underbrace{\leq}_{=E\left\{m_{1} \cdot y_{1}^{2} \cdot \bar{y}^{2}\right\}=G_{2, n} \rightarrow 0} \cdot \underbrace{E\left\{\bar{y}_{1}^{2} \cdot y^{2}\right\}}_{\begin{array}{c}
\text { Lemma } 2
\end{array}}
\end{gathered}>0
$$

for $n \rightarrow \infty$

- $G_{3, n}$ :

$$
\begin{aligned}
& 0 \leq\left|G_{3, n}\right|=\left|E\left\{m_{1} \cdot y_{1}^{3} \cdot \bar{y}\right\}\right|=\frac{1}{n} \cdot\left|E\left\{m_{1} \cdot y_{1}^{4}\right\}+\sum_{i=2}^{n} E\left\{m_{1} \cdot y_{1}^{3} \cdot y_{i}\right\}\right| \\
& \underset{(2)}{=} \frac{1}{n} \cdot E\left\{m_{1} \cdot y_{1}^{4}\right\}=\frac{v_{4}}{n} \rightarrow 0 \text { for } n \rightarrow \infty
\end{aligned}
$$

Term $H_{n}$
For term $H_{n}$ it is obtained:
$0 \leq\left|H_{n}\right|=$
$\left|E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{4}\right\}\right| \underset{(*)}{\leq} E\left\{\left|l_{1}\right| \cdot\left|y_{1}-\bar{y}\right|^{4}\right\} \underset{\text { Lemma } 1}{幺} \mathrm{E}\left\{\left.\bar{y}\right|^{4}\right\} \underset{\text { Corollary }}{\rightarrow 0}$ for $n \rightarrow \infty$.

Inequality $\left(^{*}\right)$ rests upon the well-known relation $|E\{X\}| \leq E\{|X|\}$.
$\underline{\operatorname{Term} n \cdot c_{n}{ }^{2}}$
Since $n \cdot c_{n}$ converges to $1, n \cdot c_{n}{ }^{2}$ converges to 0 for $n \rightarrow \infty$.
Summary
Putting together all the intermediate results, $n \cdot c_{n}{ }^{2} \cdot D_{n}$ converges to 0 for $n \rightarrow \infty$.

Appendix 3.2. Analysis of $\boldsymbol{n} \cdot(\boldsymbol{n}-\mathbf{1}) \cdot \boldsymbol{c}_{\boldsymbol{n}}{ }^{2} \cdot \boldsymbol{F}_{\boldsymbol{n}}$ from Formula (14)

$$
\begin{aligned}
& F_{n}=E\left\{\left(m_{1}+l_{1}\right) \cdot\left(m_{2}+l_{2}\right) \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\} \\
& =\underbrace{E\left\{m_{1} \cdot m_{2} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}}_{=: F_{1, n}}+2 \\
& \cdot \underbrace{E\left\{m_{1} \cdot l_{2} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}}_{=: F_{2, n}}+\underbrace{E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot l_{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}}_{=: F_{3, n}}
\end{aligned}
$$

Term $F_{2, n}$
It holds

$$
\begin{gathered}
0 \leq\left|F_{2, n}\right|=\left|E\left\{m_{1} \cdot l_{2} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}\right| \\
\varliminf_{(*)}^{\leq} E\left\{\left|m_{1} \cdot l_{2} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right|\right\} \underset{\begin{array}{c}
\text { nonnegativity } \\
\text { of all } \\
\text { components }
\end{array}}{=} E\left\{m_{1} \cdot\left(y_{1}-\bar{y}\right)^{2}\right.
\end{gathered}
$$

$$
\left.\cdot\left|l_{2}\right| \cdot\left|\left(y_{2}-\bar{y}\right)^{2}\right|\right\}
$$

$$
\underset{\text { Lemma } 1}{\vdots} E\left\{m_{1} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot|\bar{y}|^{2}\right\}=E\left\{m_{1} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot \bar{y}^{2}\right\}
$$

$$
=\underbrace{E\left\{m_{1} \cdot y_{1}{ }^{2} \cdot \bar{y}^{2}\right\}}_{=G_{2, n}}-2 \cdot \underbrace{E\left\{m_{1} \cdot y_{1} \cdot \bar{y}^{3}\right\}}_{=G_{1, n}}+\underbrace{E\left\{m_{1} \cdot \bar{y}^{4}\right\}}_{=G_{0, n}} .
$$

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Inequality $\left(^{*}\right)$ rests upon the well-known relation $|E\{X\}| \leq E\{|X|\}$.
Since $G_{0, n} \rightarrow 0, G_{1, n} \rightarrow 0$, and $G_{2, n} \rightarrow 0$ for $n \rightarrow \infty,\left|F_{2, n}\right|$ and, thus, $F_{2, n}$ converges to 0 for $n \rightarrow \infty$.
$\underline{\text { Term } F_{3, n}}$

$$
\begin{aligned}
& \quad 0 \leq\left|F_{3, n}\right|=\left|E\left\{l_{1} \cdot\left(y_{1}-\bar{y}\right)^{2} \cdot l_{2} \cdot\left(y_{2}-\bar{y}\right)^{2}\right\}\right| \\
& \underset{(*)}{\leq} E\left\{\left|l_{1}\right| \cdot\left|y_{1}-\bar{y}\right|^{2} \cdot\left|l_{2}\right| \cdot\left|y_{2}-\bar{y}\right|^{2}\right\} \underbrace{\leq}_{\text {Lemma } 1} \mathrm{E}\left\{\left.\bar{y}\right|^{2} \cdot|\bar{y}|^{2}\right\}= \\
& \mathrm{E}\left\{|\bar{y}|^{4}\right\} \underset{\text { Corollary }}{\rightarrow 0} \text { for } n \rightarrow \infty .
\end{aligned}
$$

Inequality $\left(^{*}\right.$ ) rests upon the well-known relation $|E\{X\}| \leq E\{|X|\}$.
Since $\left|F_{3, n}\right| \rightarrow 0$ for $n \rightarrow \infty, F_{3, n}$ converges to 0 for $n \rightarrow \infty$.
$\frac{\text { Term } F_{1, n}}{F_{1, n}}$

$$
\begin{aligned}
= & E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}-E\left\{m_{1} \cdot m_{2} \cdot\left[y_{1}^{2} \cdot 2 \cdot y_{2} \cdot \bar{y}+y_{2}^{2} \cdot 2 \cdot y_{1} \cdot \bar{y}\right]\right\} \\
& +E\left\{m_{1} \cdot m_{2} \cdot\left[y_{1}^{2} \cdot \bar{y}^{2}+y_{2}^{2} \cdot \bar{y}^{2}\right]\right\}+4 \cdot E\left\{m_{1} \cdot m_{2} \cdot y_{1} \cdot y_{2} \cdot \bar{y}^{2}\right\} \\
& -2 \cdot E\left\{m_{1} \cdot m_{2} \cdot\left[y_{1} \cdot \bar{y}^{3}+y_{2} \cdot \bar{y}^{3}\right]\right\}+E\left\{m_{1} \cdot m_{2} \cdot \bar{y}^{4}\right\} .
\end{aligned}
$$

Since $y_{1}, \ldots, y_{n}$ are independent and identically distributed and $E\left\{m_{1} \cdot y_{1}^{2}\right\}=\sigma_{-}^{2}$, it is obtained
(5)

$$
\begin{gathered}
F_{1, n}=\sigma_{-}^{4}-2 \cdot 2 \cdot \underbrace{E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2} \cdot \bar{y}\right\}}_{=: J_{1, n}} \\
+2 \cdot \underbrace{E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot \bar{y}^{2}\right\}}_{=: J_{2, n}}+4 \cdot \underbrace{E\left\{m_{1} \cdot m_{2} \cdot y_{1} \cdot y_{2} \cdot \bar{y}^{2}\right\}}_{=: J_{3, n}} \\
-2 \cdot 2 \cdot \underbrace{E\left\{m_{1} \cdot m_{2} \cdot y_{1} \cdot \bar{y}^{3}\right\}}_{=: J_{4, n}}+\underbrace{E\left\{m_{1} \cdot m_{2} \cdot \bar{y}^{4}\right\}}_{=: J_{5, n}} .
\end{gathered}
$$

It suffices to show that the terms $J_{1, n}, \ldots, J_{5, n}$ converge to 0 , to prove $F_{1, n} \rightarrow \sigma_{-}^{4}$.

- $J_{1, n}$ :

$$
\begin{aligned}
& 0 \leq\left|J_{1, n}\right|=\left|E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2} \cdot \bar{y}\right\}\right|= \\
& \left|E\left\{\frac{1}{n} \cdot m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2} \cdot\left(y_{1}+y_{2}+\sum_{i=3}^{n} y_{i}\right)\right\}\right|=
\end{aligned}
$$

$$
\frac{1}{n} \cdot\left|E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{3} \cdot y_{2}\right\}+E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}+\sum_{i=3}^{n} E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2} \cdot y_{i}\right\}\right|
$$

$$
\begin{gathered}
\quad=\frac{1}{n} \cdot\left|E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{3} \cdot y_{2}\right\}+E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}\right| \\
\underset{(2)}{=} \frac{1}{n} \cdot|E\left\{m_{1} \cdot y_{1}^{3} \cdot m_{2} \cdot y_{2}\right\}+\underbrace{E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}}_{(5)}|=\frac{1}{n} \cdot\left|v_{3} \cdot v_{1}+\sigma_{-}^{4}\right| \rightarrow 0
\end{gathered}
$$

for $n \rightarrow \infty$.

- $J_{2, n}$ :

$$
\begin{aligned}
& 0 \leq\left|J_{2, n}\right| \\
& =\left|E\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot \bar{y}^{2}\right\}\right| \underbrace{\sum_{\begin{array}{c}
-E\left\{m_{1} \cdot y_{y}^{4}\right\}=G_{4, n} \\
\text { bounded }
\end{array}}^{E\left\{m_{1}^{2} \cdot y^{4}\right\}} \cdot \underbrace{E\left\{m_{0}^{2} \cdot \bar{y}^{4}\right\}}_{=\left\{m_{2} \cdot \bar{y}^{4}\right\}=G_{0, n} \rightarrow 0}}_{\begin{array}{c}
\text { Cauchy-Schwarz } \\
\text { inequality }
\end{array}} \\
& \rightarrow 0
\end{aligned}
$$

for $n \rightarrow \infty$.
$\bullet J_{3, n}:$
$0 \leq\left|J_{3, n}\right|$
\(=\left|E\left\{m_{1} \cdot m_{2} \cdot y_{1} \cdot y_{2} \cdot \bar{y}^{2}\right\}\right| \underset{\begin{array}{c}Cauchy-Schwarz <br>

inequality\end{array}}{\)| $\sqrt{E\left\{m_{1}^{2} \cdot m_{2}^{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}} \cdot \underbrace{E\left\{\bar{y}^{4}\right\}}_{=\left\{m_{1} \cdot m_{2} \cdot y_{1}^{2} \cdot y_{2}^{2}\right\}=\sigma_{-}^{4}}$ |
| :--- |
|  Lemma 2  |$}$

$\rightarrow 0$
for $n \rightarrow \infty$.

- $J_{4, n}$ :

$$
\begin{aligned}
& 0 \leq\left|J_{4, n}\right| \\
& =\mid E\left\{m_{1} \cdot m_{2} \cdot y_{1}\right. \\
& \left.\cdot \bar{y}^{3}\right\} \left\lvert\,{ }_{\begin{array}{c}
\text { Cauchy-schwarz } \\
\text { inequality }
\end{array}}^{\vdots} \sqrt{\underbrace{E\left\{m_{1}^{2} \cdot y_{1}^{2} \cdot \bar{y}^{2}\right\}}_{=E\left\{m_{1} \cdot \cdot_{1}^{2} \cdot \bar{y}^{2}\right\}=G_{2, n} \rightarrow 0} \cdot \underbrace{E\left\{m_{2}^{2} \cdot \bar{y}^{4}\right\}}_{=E\left\{m_{2} \cdot \bar{y}^{4}\right\}=G_{0, n} \rightarrow 0}} \rightarrow 0\right.
\end{aligned}
$$

for $n \rightarrow \infty$

- $J_{5, n}$ :

$$
0 \leq J_{5, n}=E\left\{m_{1} \cdot m_{2} \cdot \bar{y}^{4}\right\} \leq \underbrace{E\left\{\bar{y}^{4}\right\}}_{\substack{\rightarrow 0 \\ \text { Lemma } 2}} \rightarrow 0 \text { for } n \rightarrow \infty .
$$



## Summary

It is obtained:

$$
F_{1, n} \rightarrow \sigma_{-}^{4}, F_{n} \rightarrow \sigma_{-}^{4} \text { and } n \cdot(n-1) \cdot c_{n}^{2} \rightarrow 1
$$

These three results in combination lead to $E\left\{t_{n}{ }^{2}\right\} \rightarrow \sigma_{-}^{4}$ (in Equation (14)).

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## OPTYMALNE ESTYMATORY SEMIWARIANCJI: KOREKTA DOWODU JOSEPHY'EGO-ACZELA

Streszczenie: Semiwariancja jest intuicyjną miarą ryzyka, ponieważ koncentruje się na wartościach osiąganych poniżej celu, a nie na całkowitej zmienności. Aby z powodzeniem stosować semiwariancję w praktyce, potrzebny jest estymator semiwariancji; Josephy i Aczel podają takie oszacowanie. Niestety wspomniani autorzy nie udowodnili poprawnie asymptotycznej spójności i średniej kwadratowej błędów estymatora. Ich dowód zawiera bowiem błąd. Prezentowany artykuł koryguje błąd obliczeniowy w oryginalnym dowodzie Josephy'ego i Aczela i w ten sposób dostarcza badaczom i praktykom narzędzie m.in. do wyboru efektywnego portfela oraz pomiaru ryzyka.

Słowa kluczowe: analiza ryzyka, semiwariancja, estymacja statystyczna.

